

Corrigé

I 1) a) $z = \frac{(\sqrt{3} + i + \sqrt{3}i - 1)(1 - i\sqrt{3})}{4} = \frac{\sqrt{3} + 1 + i\sqrt{3} - 1 - 3i + \sqrt{3} + 3 + i\sqrt{3}}{4}$
 $z = \frac{2 + 2\sqrt{3} + (-2 + 2\sqrt{3})i}{4} = \boxed{\frac{1 + \sqrt{3}}{2} + \frac{-1 + \sqrt{3}}{2}i}$

b) $z = \frac{[\sqrt{2}, \frac{\pi}{4}][2, \frac{\pi}{6}]}{[2, \frac{\pi}{3}]} = [\sqrt{2}, \frac{\pi}{4} + \frac{\pi}{6} - \frac{\pi}{3}] = [\sqrt{2}, \frac{3\pi + 2\pi - 4\pi}{12}] = [\sqrt{2}, \frac{\pi}{12}]$
 $z = \boxed{\sqrt{2}(\cos \frac{\pi}{12} + i \sin \frac{\pi}{12})}$

c) Soit $S = [r, \theta]$ avec $r > 0$ et $\theta \in \mathbb{R}$.

$S^3 = z \Leftrightarrow [r^3, 3\theta] = [\sqrt{2}, \frac{\pi}{12}]$
 $\Leftrightarrow \begin{cases} r^3 = \sqrt{2} = 2^{\frac{1}{2}} \\ 3\theta = \frac{\pi}{12} + k2\pi, k \in \mathbb{Z} \end{cases}$
 $\Leftrightarrow \begin{cases} r = 2^{\frac{1}{9}} = \sqrt[9]{2} \\ \theta = \frac{\pi}{36} + k\frac{2\pi}{3}, k \in \mathbb{Z} \end{cases}$

Racines cubiques de z : $\boxed{[\sqrt[9]{2}, \frac{\pi}{36}], [\sqrt[9]{2}, \frac{25\pi}{36}], [\sqrt[9]{2}, \frac{49\pi}{36}]}$

2) $\Delta = (5 + 7i)^2 - 4(1+i)(10+4i)$
 $= 25 + 70i - 49 - 4(10 + 4i + 10i - 4) = -24 + 70i - 24 - 56i$
 $= -48 + 14i$

Soit $S = x + iy$ avec $x \in \mathbb{R}$ et $y \in \mathbb{R}$.

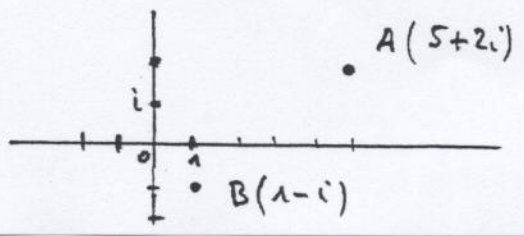
$S^2 = -48 + 14i \Leftrightarrow \begin{cases} x^2 - y^2 = -48 & (1) \\ xy = 7 & (2) \\ x^2 + y^2 = \sqrt{48^2 + 14^2} = 50 & (3) \end{cases}$

(1) + (3): $2x^2 = 2 \quad | \quad (3) - (1): 2y^2 = 98 \quad | \quad (2) \text{ } x \text{ et } y \text{ sont de même signe}$
 $x^2 = 1 \quad | \quad y^2 = 49$

Finalement: $S = 1 + 7i$ ou $S = -1 - 7i$

Solutions: $z_1 = \frac{5 + 7i + 1 + 7i}{2(1+i)} = \frac{6 + 14i}{2(1+i)} = \frac{3 + 7i}{1+i} = \frac{(3+7i)(1-i)}{2}$
 $z_1 = \frac{3 - 3i + 7i + 7}{2} = 5 + 2i$
 $z_2 = \frac{5 + 7i - 1 - 7i}{2(1+i)} = \frac{4}{2(1+i)} = \frac{2}{1+i} = \frac{2(1-i)}{2} = 1 - i$

$S = \{5 + 2i, 1 - i\}$



$$3) z_1 = \sqrt{2} + \sqrt{2}i$$

$$r_1 = \sqrt{2+2} = 2$$

$$\cos \alpha_1 = \frac{\sqrt{2}}{2}$$

$$\sin \alpha_1 = \frac{\sqrt{2}}{2}$$

$$z_1 = \left[2, \frac{\pi}{4} \right]$$

$$z_2 = \frac{\sqrt{3}}{\sqrt{5}} + \frac{1}{\sqrt{5}}i$$

$$r_2 = \sqrt{\frac{3}{5} + \frac{1}{5}} = \sqrt{\frac{4}{5}} = \frac{2}{\sqrt{5}}$$

$$\cos \alpha_2 = \frac{\frac{\sqrt{3}}{\sqrt{5}}}{\frac{2}{\sqrt{5}}} = \frac{\sqrt{3}}{2}$$

$$\sin \alpha_2 = \frac{\frac{1}{\sqrt{5}}}{\frac{2}{\sqrt{5}}} = \frac{1}{2}$$

$$z_2 = \left[\frac{2}{\sqrt{5}}, \frac{\pi}{6} \right]$$

$$a) \frac{z_1}{z_2} = \frac{\left[2, \frac{\pi}{4} \right]}{\left[\frac{2}{\sqrt{5}}, \frac{\pi}{6} \right]} = \left[\frac{2}{\frac{2}{\sqrt{5}}}, \frac{\pi}{4} - \frac{\pi}{6} \right] = \left[\sqrt{5}, \frac{\pi}{12} \right]$$

$$\boxed{\frac{z_1}{z_2} = \sqrt{5} \left(\cos \frac{\pi}{12} + i \sin \frac{\pi}{12} \right)}$$

$$b) \frac{z_1}{z_2} = \frac{\sqrt{2} + \sqrt{2}i}{\frac{\sqrt{3} + i}{\sqrt{5}}} = \frac{\sqrt{5}\sqrt{2}(1+i)}{\sqrt{3} + i} = \frac{\sqrt{10}(1+i)(\sqrt{3}-i)}{4}$$

$$\boxed{\frac{z_1}{z_2} = \frac{\sqrt{10}}{4} \left[(\sqrt{3}+1) + i(\sqrt{3}-1) \right]}$$

$$c) \sqrt{5} \cos \frac{\pi}{12} = \frac{\sqrt{10}}{4} (\sqrt{3}+1)$$

$$\sqrt{5} \sin \frac{\pi}{12} = \frac{\sqrt{10}}{4} (\sqrt{3}-1)$$

$$\boxed{\begin{aligned} \cos \frac{\pi}{12} &= \frac{\sqrt{2}}{4} (\sqrt{3}+1) = \frac{\sqrt{6} + \sqrt{2}}{4} \\ \sin \frac{\pi}{12} &= \frac{\sqrt{2}}{4} (\sqrt{3}-1) = \frac{\sqrt{6} - \sqrt{2}}{4} \end{aligned}}$$

$$\text{II } 1) \quad A \cdot B = \begin{pmatrix} 1 & -1 & 2 \\ 2 & -1 & 6 \\ 1 & 2 & \lambda \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 2 \\ 0 & 0 & 6 \\ 0 & 0 & \lambda \end{pmatrix}$$

$$B \cdot A = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & -1 & 2 \\ 2 & -1 & 6 \\ 1 & 2 & \lambda \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 2 & \lambda \end{pmatrix}$$

On a : $A \cdot B \neq B \cdot A$

$$2) \quad \begin{vmatrix} 1 & -1 & 2 \\ 2 & -1 & 6 \\ 1 & 2 & \lambda \end{vmatrix} = -\lambda + 8 - 6 + 2 - 12 + 2\lambda = \lambda - 8$$

3) A est singulière $\Leftrightarrow \det A = 0 \Leftrightarrow \lambda - 8 = 0 \Leftrightarrow \lambda = 8$

$$4) \quad A^{-1} = \frac{1}{\det A} \text{adj. } A$$

$$= \frac{1}{-8} \begin{pmatrix} -12 & 4 & -4 \\ 6 & -2 & -2 \\ 5 & -3 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{3}{2} & -\frac{1}{2} & \frac{1}{2} \\ -\frac{3}{4} & \frac{1}{4} & \frac{1}{4} \\ -\frac{5}{8} & \frac{3}{8} & -\frac{1}{8} \end{pmatrix}$$

$$\text{III} \quad \begin{cases} mx + y + z = 1 \\ x + z = 1 \\ x + y = 1 \end{cases} \quad (E)$$

$$\Delta = \begin{vmatrix} m & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{vmatrix} \stackrel{C_1/C_1 - C_2}{=} \begin{vmatrix} m-1 & 1 & 1 \\ 1 & 0 & 1 \\ \boxed{0} & 1 & 0 \end{vmatrix} = - \begin{vmatrix} m-1 & 1 \\ 1 & 1 \end{vmatrix}$$

$$= -(m-1-1) = -(m-2) = 2-m$$

$$\boxed{\Delta = 2-m}$$

$$\boxed{1^{er} \text{ cas}} \quad \Delta = 0 \Leftrightarrow 2-m = 0 \Leftrightarrow \boxed{m = 2}$$

$$(E) \Leftrightarrow \begin{cases} 2x + y + z = 1 & (1) \\ x + z = 1 & (2) \\ x + y = 1 & (3) \end{cases} \Leftrightarrow \begin{cases} (2) \quad z = 1-x \\ (1) \quad 2x + y + 1 - x = 1 \\ (3) \quad x + y = 1 \end{cases} \Leftrightarrow \begin{cases} z = 1-x \\ x + y = 0 \\ x + y = 1 \end{cases}$$

impossible

$$\boxed{S = \emptyset}$$

Dans un repère de l'espace (E) est un système de trois plans n'ayant aucun point commun.

$$\boxed{2^{er} \text{ cas}} \quad \Delta \neq 0 \Leftrightarrow \boxed{m \neq 2}$$

$$\Delta_x = \begin{vmatrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{vmatrix} \stackrel{C_1/C_1 - C_2}{=} \begin{vmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{vmatrix} = - \begin{vmatrix} 0 & 1 \\ 1 & 1 \end{vmatrix} = 1$$

$$\Delta_y = \begin{vmatrix} m & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 0 \end{vmatrix} \stackrel{C_3/C_3 - C_2}{=} \begin{vmatrix} m & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & -1 \end{vmatrix} = (-1) \begin{vmatrix} m & 1 \\ 1 & 1 \end{vmatrix} = -(m-1) = 1-m$$

$$\Delta_z = \begin{vmatrix} m & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{vmatrix} \stackrel{C_2/C_2 - C_3}{=} \begin{vmatrix} m & 0 & 1 \\ 1 & -1 & 1 \\ 1 & 0 & 1 \end{vmatrix} = (-1) \begin{vmatrix} m & 1 \\ 1 & 1 \end{vmatrix} = 1-m$$

$$x = \frac{\Delta_x}{\Delta} = \frac{1}{2-m} \quad ; \quad y = \frac{\Delta_y}{\Delta} = \frac{1-m}{2-m} \quad ; \quad z = \frac{\Delta_z}{\Delta} = \frac{1-m}{2-m}$$

$$\boxed{S = \left\{ \left(\frac{1}{2-m}, \frac{1-m}{2-m}, \frac{1-m}{2-m} \right) \right\}}$$

(E) est un système de trois plans sécants en un point.